# EAM 24 Top Down

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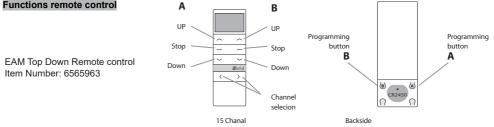
Read the manual before you begin the installation. If these instructions are not followed, this may lead to defects and injury in which warranty can't be claimed.

# warning:

Children cannot recognize the dangers of electrical equipment and may therefore not work with it. It is important to follow this instruction for your own safety.

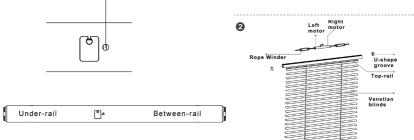
- 1. Do not operate the motor in humid surroundings.
- 2. The motor must be installed correctly.
- 3. Keep the antenna in a good condition and do not shorten. The antenna should not come into contact with other metal parts otherwise it will reduce the effect.
- 4. The motor must be protected from direct moisture influences.
- 5. erfal GmbH & Co. KG declares that this motor has been manufactured according to the guidelines of the CE standard 1999/5/EC
- 6. Warning and user information Usage only in dry places indoors; risk of electric shock and fire. Load only suitable Lithium-ion batteries of the eACCU series. Other chemicals and battery types can burst people and cause damage to property. Do your part for environ mentally friendly recycling.

# Functions remote control



Always check that the remote control is in Bi-directional mode! Refer to manuals for remote controls at:

Motor settingbutton (P1)		Signal line Motor settingbutton (P1)
Functions and installation mot	tor O	power line
Power:	8.4 W	temperature
Voltage motor:	DC 12V	Working
Amperage:	0.7 A	-10°C
• Speed:	34 RPM	
• Torque	0.6 Nm	
Technical data of the motor Torque	0.6 Nm	= <u> </u> = <sup>55∘</sup> <



Bottom-rail

# Step 1 Setting up the first channel

This action deletes all channels and final adjustments in memory.



Hold down P1 until the left and right motor is moving.

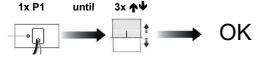
Hold down STOP A until the motor moves up and down.

The direction of rotation for both rails has been changed.

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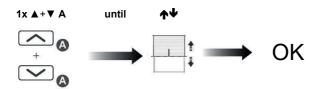
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# Step 2 Switching the between-rail with A and B



Press and hold P1 until the left and right motor moves 3x. Then let go.

# Step 3 Changing the direction of rotation (Can only be changed if no end position is set)



Press UP A and DOWN A. The motor moves 1x.

# Step 4 Setting limit position

1. Set the desired top position of both motors.



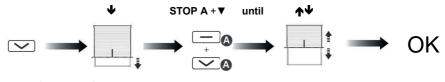
top position. Both rails move.



Use the **OPERATING-** buttons to move the product to the desired

Press up and STOP A until left and right motor moves up and down.

#### 2. Set the desired down position of both motors.

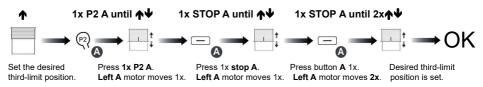


Use the **OPERATING-** buttons to move the product to the desired down position. Both rails move.

Press DOWN and STOP A until left and right motor moves up and down.

# Step 5 Setting the desired third-limit position

After setting the top and bottom position, you can set the desired third-limit position, like the half-open position.

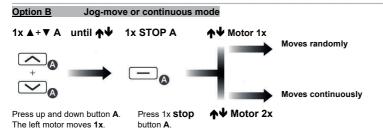


Note: Set a different third-limit position using the B buttons. Press the B button to repeat the above operation.

# Additional settings

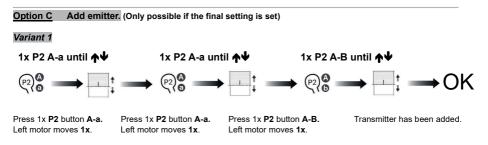
### Option A Operation left / right motor

- Running in the same direction: two motors can run up and down at the same time or run separately. The safety distance of another motor stops automatically during the operation of one motor.
- 2. Running in the opposite direction: two motors can run up and down, the other runs down or runs separately.



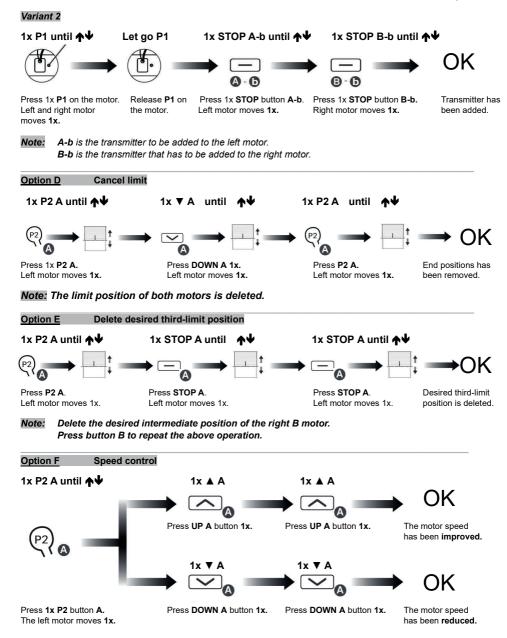
Note: set the jog-move / continuous move mode switch of the right motor, just press the B button to repeat that the above operation;

Briefly press the up / down button in jog-move mode. The motor is now in jog-move mode. If you press the up / down button for a long time in jog-move mode, the motor runs continuously.

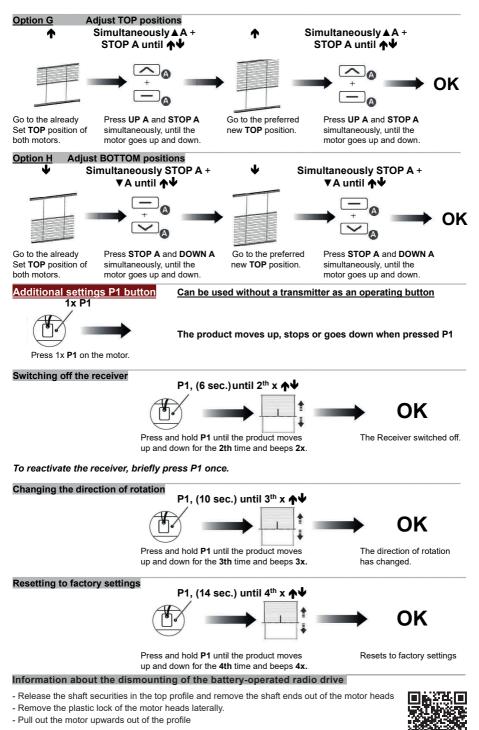


**Note:** Emitter **a** is the setting that already matches, while emitter **b** is not. Add a transmitter to the right motor of the set motor, press the **B** button to repeat the above operation. **A** is the existing transmitter and **a** is the button of the bottom rail.

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**Note:** If the motor is running without moving, indicates that the motor has the maximum or has reached a minimum value; adjust the speed of the right motor, press the **b** button to repeat the above operation.



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